

Numerical relativity in AdS/CFT by **spNDSolve**, a Mathematica package for solving PDEs by the pseudospectral method

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Outline

Introduction to numerical relativity in AdS/CFT

The pseudospectral method and **spNDSolve**

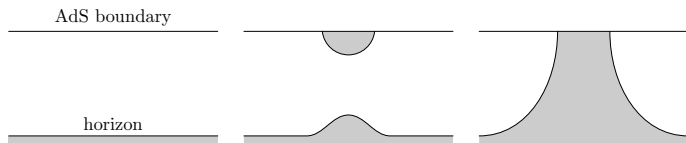
Some examples

Charged black funnel

Introduction

The absence of uniqueness theorems in AdS has following consequences

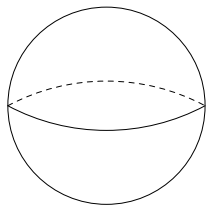
- ▶ Many matter fields can be added. Apply AdS/CFT to condensed matter physics.
- ▶
 - ▶ The topology of the horizon is not necessarily a sphere.
 - ▶ The surface gravity of a horizon is not necessarily a constant.
 - ▶ The AdS boundary can be conformal to any spacetime \mathcal{B}_d .
 - ▶ e.g., Black droplets, black funnels, localized plasma balls



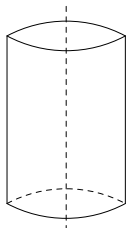
Solutions to Einstein's equation

$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R + \Lambda g_{\mu\nu} = 8\pi GT_{\mu\nu}$$

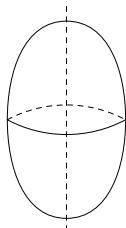
Symmetries in Spacetimes:



spherically symmetric
3 Killing vectors



cylindrically symmetric
2 Killing vectors



axially symmetric
1 Killing vector

Einstein equations for stationary, axisymmetric spacetimes are completely integrable for $\Lambda = 0$, not for $\Lambda \neq 0$.

Solutions to Einstein equations

$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R + \Lambda g_{\mu\nu} = 8\pi GT_{\mu\nu}$$

Suppose (t, r, θ, ϕ) are spacetime coordinates, where ∂_t and ∂_ϕ are Killing vectors.

- ▶ When $\Lambda = 0$, the crossing term in the metric is only $dtd\phi$. However, when $\Lambda \neq 0$, $dtdr$ and $dtd\theta$ are possible.
- ▶ In the static case, Einstein equations are still not integrable when $\Lambda \neq 0$.
- ▶ Analytic solution exists in a very special case: the C-metric.

Conclusion: Numerical relativity in AdS/CFT is important.

Gauge fixing and the DeTurck method

$$\begin{aligned}g_{\mu\nu} &: \frac{D(D+1)}{2} \text{ independent components} \\R_{\mu\nu} + \frac{D-1}{L^2} g_{\mu\nu} = 0 &: \frac{D(D-1)}{2} \text{ independent equations} \\R_{\mu\nu}^H + \frac{D-1}{L^2} g_{\mu\nu} = 0 &: \frac{D(D+1)}{2} \text{ independent equations}\end{aligned}$$

$$R_{\mu\nu} \rightarrow R_{\mu\nu}^H = R_{\mu\nu} - \nabla_{(\mu} \xi_{\nu)},$$

where

$$\xi^\mu = g^{\lambda\sigma} [\Gamma_{\lambda\sigma}^\mu(g) - \bar{\Gamma}_{\lambda\sigma}^\mu(\bar{g})],$$

and $\bar{\Gamma}_{\lambda\sigma}^\mu(\bar{g})$ is the Levi-Civita connection associated with a reference metric $\bar{g}_{\mu\nu}$.

Conformal gauge v.s. DeTurck method

A stationary solution is a solution to a well-posed boundary value problem. [1510.02804]

Consider a codimension-2, static problem. In the conformal gauge, the metric ansatz has three unknown functions:

$$ds^2 = -A(r, x)dt^2 + B(r, x)(dr^2 + dx^2) + C(r, x)dy^2$$

However, there is still remaining gauge freedom, which is imposed as boundary conditions in this case.

By the DeTurck method, the metric ansatz must be closed under $r \rightarrow f_1(r, x)$ and $x \rightarrow f_2(r, x)$:

$$ds^2 = -Tdt^2 + A dr^2 + B dx^2 + S dy^2 + 2F dr dx$$

There are five unknown functions of (r, x) .

Holographic pair density waves (PDW)

$$\mathcal{L} = R + \frac{6}{L^2} - \frac{1}{2}(\partial\chi)^2 - \frac{Z_A}{4}F^2 - \frac{Z_B}{4}\tilde{F}^2 - \frac{Z_{AB}}{2}F\tilde{F} \\ - \mathcal{K}(\chi)(\partial_\mu\theta - q_A A_\mu - q_B B_\mu)^2 - \frac{m^2}{2}\chi^2$$

The ansatz must be closed under coordinate transformations $z \rightarrow \tilde{z}(z, x)$ and $x \rightarrow \tilde{x}(z, x)$:

$$ds^2 = \frac{r_h^2}{L^2(1-z^2)^2} \left[-F(z)Q_{tt} dt^2 + \frac{4z^2L^4Q_{zz}}{r_h^2F(z)} dz^2 \right. \\ \left. + Q_{xx}(dx - 2z(1-z^2)^2Q_{xz}dz)^2 + Q_{yy}dy^2 \right]$$

$$A_t = \mu z^2\alpha, \quad B_t = z^2\beta, \quad \chi = (1-z^2)\phi,$$

where the eight functions $(\phi, \alpha, \beta, Q_{tt}, Q_{zz}, Q_{xx}, Q_{yy}, Q_{xz})$ are functions of z and x .

The pseudospectral method

- ▶ A function is vector in Hilbert space.
- ▶ A differential operator is a matrix.

In numerical calculations, we use a finite number of basis of Hilbert space to approximate the solution, so the differential operator is a finite-dimensional matrix.

- ▶ Construct the grid
- ▶ Calculate the differentiation matrix ($\frac{d}{dx}$, $\frac{d^2}{dx^2}$, *etc.*)
- ▶ Imposing boundary conditions by replacing rows corresponding to the boundaries
- ▶ Solve a linear system of equations
- ▶ Nonlinear equations = linear equations + iterations

spNDSolve

Goal: Develop a package that solves any stationary PDEs by the pseudospectral method (if applicable) by the same procedure. Only use equations and boundary conditions as inputs, just like *NDSolve*.

The basic idea of spNDSolve is as follows:

- ▶ At the first (symbolic) stage, expressions are automatically generated in *HoldForm*.
- ▶ At the second (numerical) stage, spNDSolve will assemble these expressions and execute them by *ReleaseHold*.

spNDSolve

Expressions generated at the first stage:

```
[12]:= replrule
```

```
[12]= {g1[z, x] → g1, g1(1,0)[z, x] → g1z, g1(0,1)[z, x] → g1x, g1(1,1)[z, x] → g1zx, g1(2,0)[z, x] → g1zz,
g1(0,2)[z, x] → g1xx, g2[z, x] → g2, g2(1,0)[z, x] → g2z, g2(0,1)[z, x] → g2x, g2(1,1)[z, x] → g2zx,
g2(2,0)[z, x] → g2zz, g2(0,2)[z, x] → g2xx, g3[z, x] → g3, g3(1,0)[z, x] → g3z, g3(0,1)[z, x] → g3x,
g3(1,1)[z, x] → g3zx, g3(2,0)[z, x] → g3zz, g3(0,2)[z, x] → g3xx, g4[z, x] → g4, g4(1,0)[z, x] → g4z,
g4(0,1)[z, x] → g4x, g4(1,1)[z, x] → g4zx, g4(2,0)[z, x] → g4zz, g4(0,2)[z, x] → g4xx,
g5[z, x] → g5, g5(1,0)[z, x] → g5z, g5(0,1)[z, x] → g5x, g5(1,1)[z, x] → g5zx, g5(2,0)[z, x] → g5zz,
g5(0,2)[z, x] → g5xx, At[z, x] → At, At(1,0)[z, x] → Atz, At(0,1)[z, x] → Atx, At(1,1)[z, x] → Atzx,
At(2,0)[z, x] → Atzz, At(0,2)[z, x] → Atxx, Bt[z, x] → Bt, Bt(1,0)[z, x] → Btz, Bt(0,1)[z, x] → Btx,
Bt(1,1)[z, x] → Btzx, Bt(2,0)[z, x] → Btzz, Bt(0,2)[z, x] → Btxx, phi[z, x] → phi, phi(1,0)[z, x] → phiz,
phi(0,1)[z, x] → phix, phi(1,1)[z, x] → phizx, phi(2,0)[z, x] → phizz, phi(0,2)[z, x] → phixx}
```

```
[13]:= calcdfderiv
```

```
[13]= {g1z = dz.g1, g1x = dx.g1, g1zx = dzx.g1, g1zz = dzz.g1, g1xx = dxx.g1, g2z = dz.g2,
g2x = dx.g2, g2zx = dzx.g2, g2zz = dzz.g2, g2xx = dxx.g2, g3z = dz.g3, g3x = dx.g3, g3zx = dzx.g3,
g3zz = dzz.g3, g3xx = dxx.g3, g4z = dz.g4, g4x = dx.g4, g4zx = dzx.g4, g4zz = dzz.g4, g4xx = dxx.g4,
g5z = dz.g5, g5x = dx.g5, g5zx = dzx.g5, g5zz = dzz.g5, g5xx = dxx.g5, Atz = dz.At, Atx = dx.At,
Atzx = dzx.At, Atzz = dzz.At, Atxx = dxx.At, Btz = dz.Bt, Btx = dx.Bt, Btzx = dzx.Bt, Btzz = dzz.Bt,
Btxx = dxx.Bt, phiz = dz.phi, phix = dx.phi, phizx = dzx.phi, phizz = dzz.phi, phixx = dxx.phi}
```

```

[1]:= << spNDSolve.m

setdir;
flist = {g1[z, x], g2[z, x], g3[z, x], g4[z, x], g5[z, x], At[z, x], Bt[z, x], phi[z, x]};
brylist1 = {g1[z, x] - g2[z, x], D[g2[z, x], z], D[g3[z, x], z], D[g4[z, x], z], D[g5[z, x], z], D[At[z, x], z], D[Bt[z, x], z], D[ph:
brylist2 = {g1[z, x] - 1, g2[z, x] - 1, g3[z, x] - 1, g4[z, x] - 1, g5[z, x], At[z, x] - 1, Bt[z, x], phi[z, x]};
brylist3 = {D[g1[z, x], x], D[g2[z, x], x], D[g3[z, x], x], D[g4[z, x], x], g5[z, x], D[At[z, x], x], D[Bt[z, x], x], D[phi[z, x], x]
calcbryind := ({bryind1, bryind2} = bryIndex[{1, 2}]; bryind3 = bryIndex[3, {5}]);
bryLinearize[{flist}, {{bryind1, brylist1}, {bryind2, brylist2}, {bryind3, brylist3}}];
get[eqlistmat, eqlist, xi2, z -> zaux12];
calcfref := {g1 = one; g2 = one; g3 = one; g4 = one; g5 = 0 one; At = one; Bt = a0 (1 - z^2)^3 Cos[x]; phi = -a0 (1 - z^2)^3 Cos[x]};
output := {nxi2 = Norm@arrayDrop[xi2, {bryind1, bryind2}]; PrintTemporary["ε^2=", nxi2]; {nxi2, rh, solsave}};
Off[LinearSolve::luc];

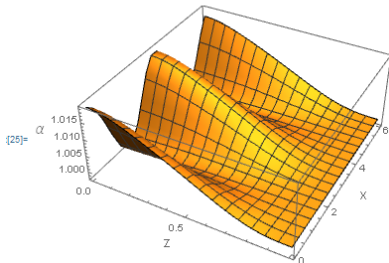
[14]= Dynamic[changes]
[14]= {0.618555, 0.100396, 0.00170137, 4.54892 × 10^-7, 1.0657 × 10^-10}

[10]= spNDSolve[{z, x}, {{# + 1 / 2 &, # &}}, {20, {20, "periodic"}}, {a, 4}, {c, -2.34}, {rh, 0.1528}, {a0, 0.04}, {q8, 0}, eqlistmatQ -> True]

Saved to outputs

[25]= ListPlot3D[{z, x, At}]^T, AxesLabel -> {Style["z", 14], Style["x", 14], Style["α ", 14]}, PlotRange -> All]

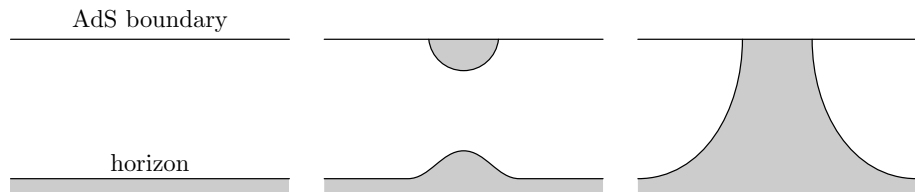
```



Charged black funnels

CFT at finite charge density in a black hole background.

$$ds^2 = \frac{L^2}{xyQH^2} \left[-x(1-y)QMdt^2 + \frac{xQH^2A dy^2}{4y(1-y)M} \right. \\ \left. + \frac{r_0^2 B [dx + x(1-x)^2 F dy]^2}{x(1-x)^4} + \frac{r_0^2 S}{(1-x)^2} d\Omega_2^2 \right]$$



Features of spNDSolve

- ▶ Grid construction
- ▶ Method of continuation
- ▶ Two-domain decomposition
- ▶ Arbitrary precision

To be improved:

- ▶ Iterative solver

Summary

spNDSolve: A Mathematica package for solving PDEs by the pseudospectral method

- ▶ Introduction to numerical relativity in AdS/CFT
 - ▶ Non-existence of uniqueness theorems
 - ▶ DeTurck method
 - ▶ Pseudospectral method
- ▶ The pseudospectral method and spNDSolve
 - ▶ Grid construction
 - ▶ Built-in continuation method
 - ▶ Two-domain decomposition
 - ▶ Arbitrary precision
- ▶ Some examples
 - ▶ Holographic superconductors
 - ▶ Charged black funnel

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